

GOOD SHEPHERD ROBE IN POSER CLOTH ROOM

PART 2

Demonstration using Dynamic Robe for M4

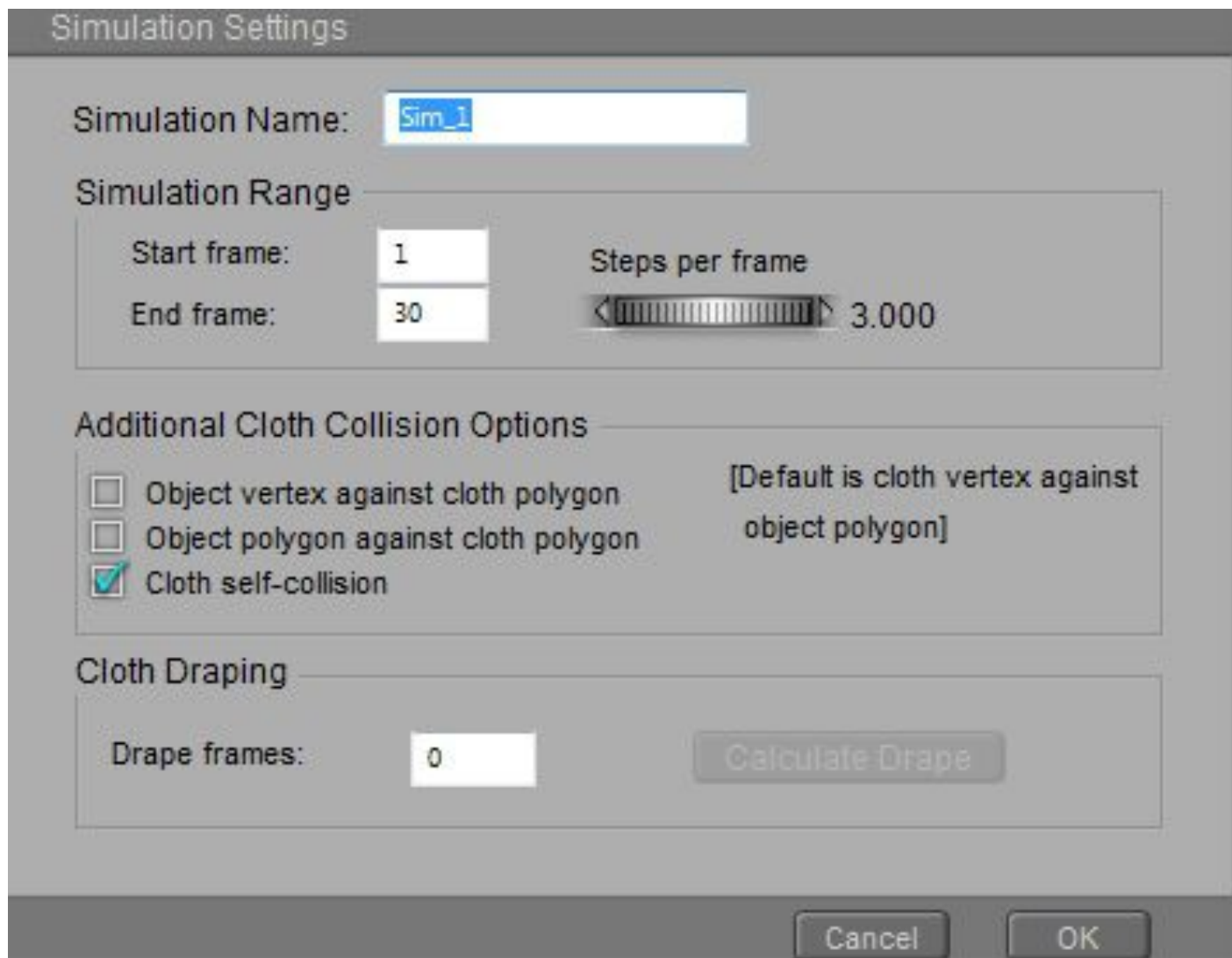
<https://www.renderosity.com/mod/freestuff/dynamic-robe-for-m4/62360>

I wanted to add this information to the original Dynamic Robes in the Cloth Room tutorial, and decided it was better to add it as a Part 2 to the original.

After working with this particular robe quite a bit, I started experimenting with the settings and felt that I was finally getting the results desired on the Good Shepherd project, so below are screen captures of the settings used.

Of note, remember that the robe is a bit long, and tends to get tangled up on the feet or sandals...so treating the cloth as being heavier, with greater fold resistance, overcomes this issue.

~skylab :)



Cloth Collision Objects

Current collision object:

▼ SickleStocks M4 [Add/Remove...](#)

Collision Offset

1.000

Collision Depth

1.000

Static Friction

0.500

Dynamic Friction

0.100

Figure Collision Options

Start draping from zero pose

Ignore head collisions

Ignore hand collisions

Ignore feet collisions

Cancel

OK

1. Cloth Simulations

▼ Sim_1

New Simulation...

Delete Simulation

Simulation Settings...

2. Cloth Objects

▼ robe_1

Clothify...

Unclothify

Collide Against...

3. Cloth Groups

[robe_1]

Dynamic Group: ▼ _default

New Dynamic Group...

Delete Dynamic Group

Edit Dynamic Group...

Edit Choreographed Group...

Edit Constrained Group...

Edit Soft Decorated Group...

Edit Rigid Decorated Group...

4. Dynamics Controls

[robe_1]

Calculate Simulation

Play Simulation

Collision Friction

Fold Resistance

10.000

Shear Resistance

50.000

Stretch Resistance

50.000

Stretch Damping

0.0100

Cloth Density

0.0300

Cloth Self-friction

0.0000

Static Friction

0.5000

Dynamic Friction

0.1000

Air Damping

0.0200

Clear Simulation

Reset

Python Scripts

Wardrobe Wizard

Geom Mods

Utility Funcs

Sample Callbacks

Render / IO

Material Mods

Print Info

Prop Samples

...

Clear Buttons

